

## CprE 288 Lab Evaluation Form – Lab 9

Lab Partners \_\_\_\_\_  
 \_\_\_\_\_

Section/Lab Time \_\_\_\_\_

Done	Roles	Description	Points
		Prelab questions (5)	
	DRIVER:  NAVIGATOR:	Part 1: Pulse the sensor, check for reasonable behavior (10) <ul style="list-style-type: none"> <li>• Flash PING light (or show PING sensor being triggered with an oscilloscope) once per second.</li> <li>• Show with the oscilloscope that the PING sensor is responding reasonably to an object being moved to different distances in front of the Cybot.</li> </ul>	
	DRIVER:  NAVIGATOR:	Part 2: Sensor signal measurement (15) <ul style="list-style-type: none"> <li>• Determine pulse width in clock cycles, print the number of clock cycles to the LCD</li> <li>• Show that the time in clocks cycles, matches the time measured with the oscilloscope</li> </ul>	
	DRIVER:  NAVIGATOR:	Part 3: Continuous distance measurement (15) <ul style="list-style-type: none"> <li>• Compute and display PING sensor pulse time</li> <li>• Compute and display object distance</li> <li>• Account for overflow?</li> </ul>	
		Coding quality (5) <ul style="list-style-type: none"> <li>• Are there warning messages?</li> <li>• TA feedback to improve for next lab</li> </ul>	
		Bonus (2 pts): IR auto-calibration <ul style="list-style-type: none"> <li>• Makes use of Movement, IR, and UART APIs you created in previous labs, to help automate calibrating the IR sensor.</li> </ul>	

**Turn in for Lab 8:** Evaluation form with TA signature

TA Signature \_\_\_\_\_

Date \_\_\_\_\_

Subtotal \_\_\_\_\_

Late Penalty \_\_\_\_\_

Score \_\_\_\_\_ / 50