

# EE 475 Quiz 07

Name: Sol

1. For a unity feedback control system with open loop transfer function  $G_o(s)$  and only a reference input  $r(s)$ ,

- the position error constant  $K_p = \lim_{s \rightarrow 0} G_o(s)$ ,  $G_d(0)$
- the velocity error constant  $K_v = \lim_{s \rightarrow 0} s G_o(s)$ ,  $s G_d(s) / s = 0$
- the acceleration error constant  $K_a = \lim_{s \rightarrow 0} s^2 G_o(s)$ ,  $s^2 G_d(s) / s = 0$
- the ess due to a step  $r(s)$  is  $e_{ss2step} = \frac{1}{1+K_p}$
- the ess due to a ramp  $r(s)$  is  $e_{ss2ramp} = \frac{1}{K_v}$
- the ess due to an acceleration  $r(s)$  is  $e_{ss2acc} = \frac{1}{K_a}$
- If system type = 1,  $e_{ss2step} = 0$ , and  $e_{ss2acc} = \infty$

2. In the regular case of using the Routh criteria, we can make two statements after

the table is constructed. The two statements are: no sign change in 1st col.

- The characteristic polynomial is A.S. if 1st col have the same sign
- The number of sign changes in the 1<sup>st</sup> col = # poles in RHP.