

Communication system performance revisited

1

Slide from before: Performance Concerns

- DC offset
- Image rejection
- Quadrature requirements
- Noise and noise figure
- Phase noise and Jitter
- Distortion
 - Compression
 - Desensitization
 - Cross modulation
 - Intermodulation
 - IP2, IP3
 - Harmonic distortion (THD, SFDR,...)
- Bit error rate
- Data rate (bandwidth)

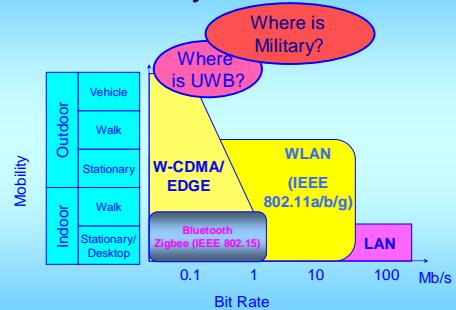
2

System level concerns

- Data rate (voice, text, image, video,...)
- Cost (CMOS, SiGe, ...)
- Mobility (fixed, indoor, outdoor, ground vehicle, airborne, ...)
- Battery life (power consumption)
- Weight (discrete, multi-chip, single chip,)
- Multi-standard support (hardware sharing)
- Security (baseband DSP)
- Quality of service (protocol, transceiver)

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Mobility vs. Bit Rate



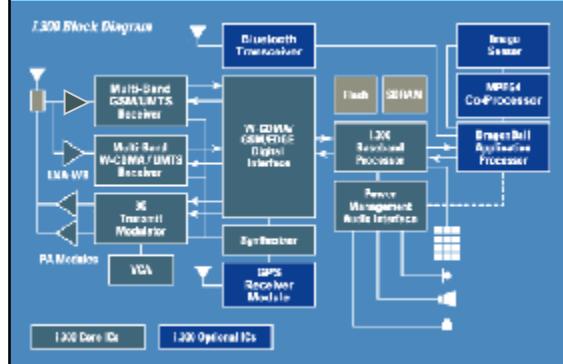
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Cost vs. Bit Rate



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Motorola 3G Smart Phone Architecture

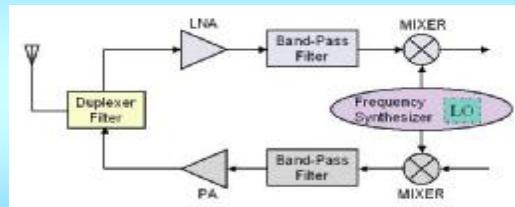


Transceiver performance

- Transceiver Overview
- Transmitter Performance Spec.
- Transmitter Architecture
- Receiver Performance Spec.
- Receiver Architecture
- Receiver Link Budget

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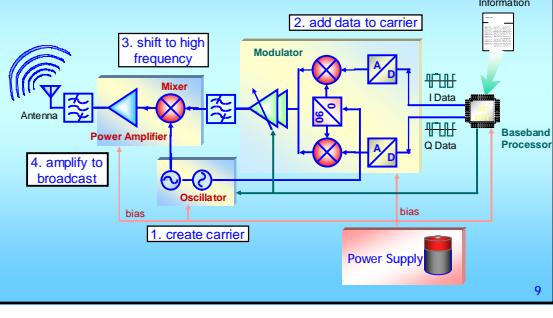
Generic Transceiver Architecture



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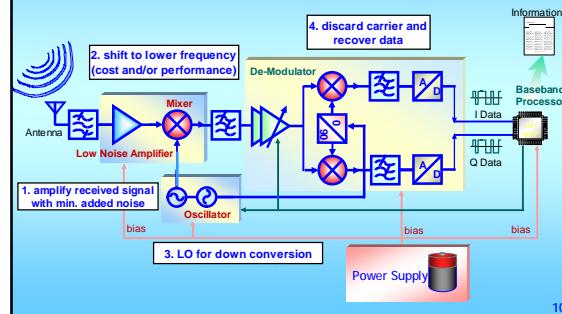
Transceiver

Role of a Transmitter



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Role of a Receiver



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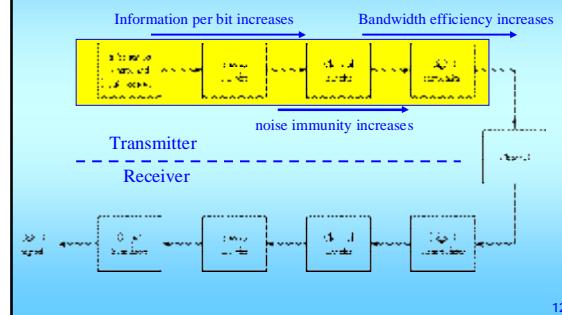
Transmitter Performance Spec.

- Output Power
- Spurious Emission
- Adjacent Channel Power Ratio; ACPR
- Frequency Stability
- Data rate
- Bandwidth efficiency
- Noise immunity



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Digital Communication System:



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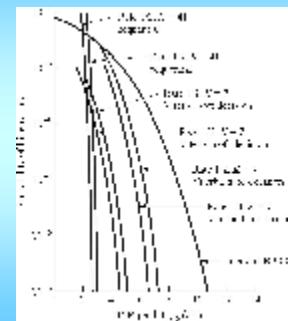
Increasing Information

- Information in a source
 - Mathematical Models of Sources
 - Information Measures
- Compressing information
 - Huffman encoding
 - Lempel-Ziv-Welch Algorithm
 - Optimal Compression?
- Quantization of analog data
 - Scalar Quantization
 - Vector Quantization
 - Model Based Coding
 - μ -law encoding
 - Delta Modulation
 - Linear Predictor Coding (LPC)

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Increasing Noise Immunity

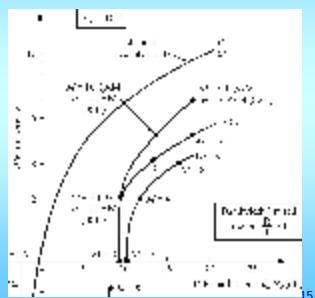
- Error correction coding
- Block coding
- Channel coding
- Adaptive feedback coding
- ...
- Diversity
- Space time diversity



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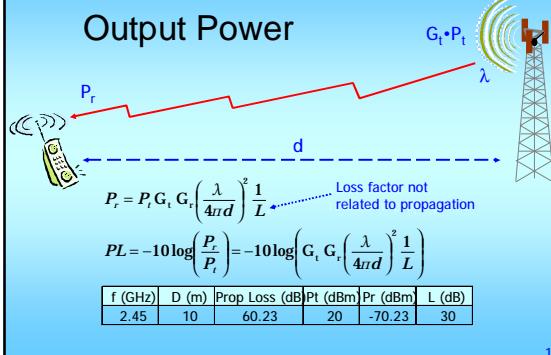
Increasing bandwidth Efficiency

- Modulation of digital data into analog waveforms
 - Impact of Modulation on Bandwidth efficiency



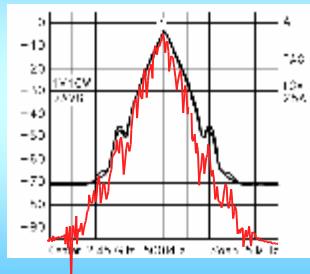
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Output Power



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Spurious Emission

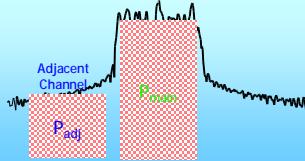


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Adjacent Channel Power Ratio

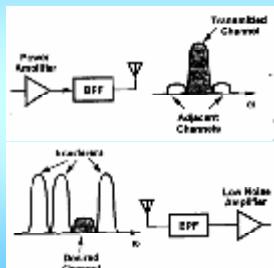
- Definition depends on specification

$$ACPR = \frac{P_{adjacent}}{P_{main}}$$



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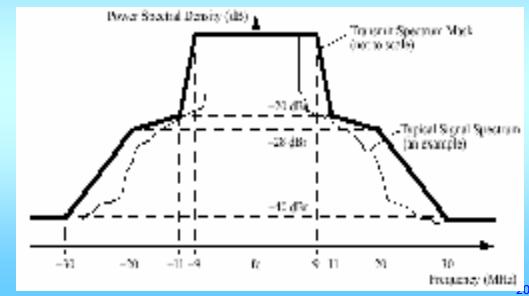
Adjacent channel reject



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Transmit Specifications

- Transmit spectrum mask



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Transmitter Architecture

- RF/BB Interface
- Direct Conversion Transmitter
- Two-step Conversion Transmitter
- Offset PLL Transmitter

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RF/BB Interface

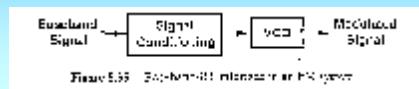


Figure 5.39 Block diagram of RF/BB interface

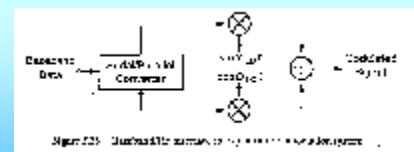


Figure 5.38 Block diagram of direct down-conversion transmitter

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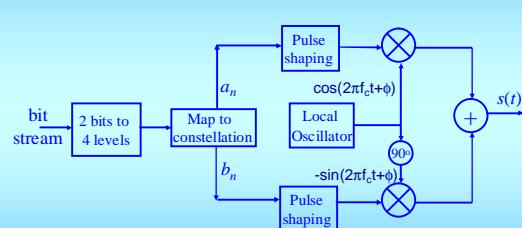
BPSK Transmitter

$$\text{Bit 1: } A \xrightarrow{\otimes} \cos(2\pi f_c t + q_c) \\ \text{Bit 0: } -A \xrightarrow{\otimes} \cos(2\pi f_c t + q_c)$$

$$s_{BPSK}(t) = \sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_c t + q_c) \quad (\text{bit 1}) \\ s_{BPSK}(t) = -\sqrt{\frac{2E_b}{T_b}} \cos(2\pi f_c t + q_c) \quad (\text{bit 0})$$

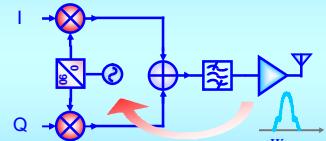
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QPSK transmitter



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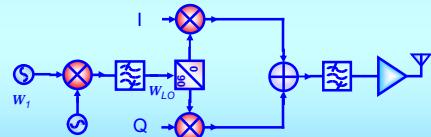
- Direct-conversion transmitter



Pros: less spurious synthesized
Cons: more LO pulling

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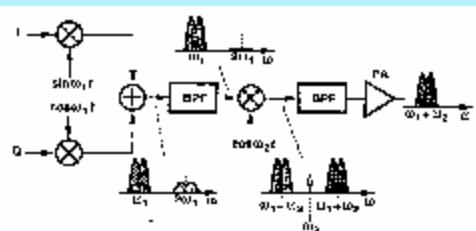
- Direct-conversion transmitter with offset LO



Pros: less LO pulling
Cons: more spurious synthesized

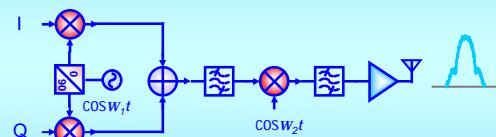
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- Two-Step Transmitters



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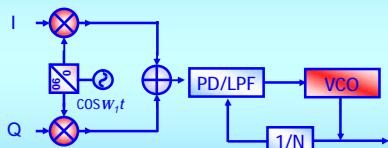
- Two-step transmitter



Pros: less LO pulling
superior IQ matching
Cons: required high-Q bandpass filter

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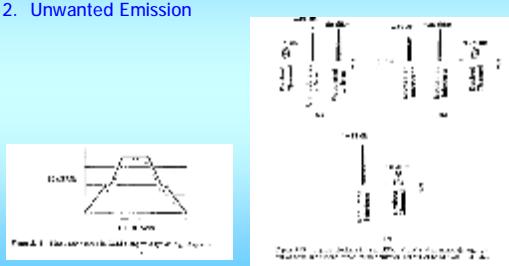
- Offset PLL transmitter



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Transmitter Performance Check

1. Sensitivity and Dynamic Range
2. Unwanted Emission



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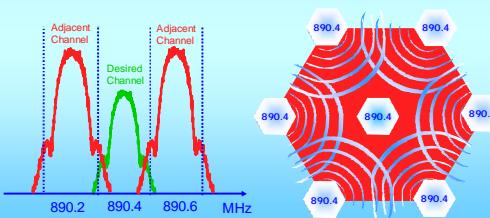
Receiver Performance Spec.

- Sensitivity
- Selectivity
- Spurious Response Rejection
- Intermodulation Rejection
- Receiver Self-quieting
- Dynamic Range

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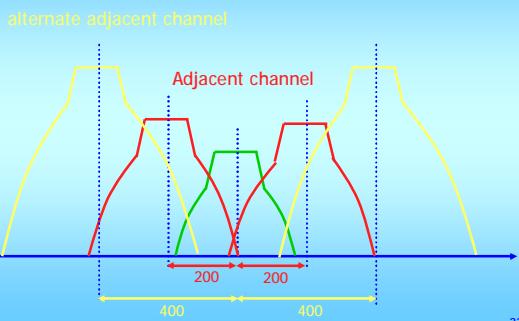
Sensitivity

- Adjacent Channel Interference
- Co-Channel Interference



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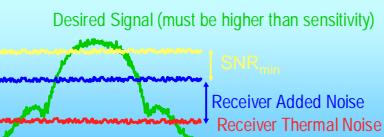
Receiver Specifications



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Sensitivity

$$\begin{aligned} \text{Noise Floor} &= P_{nf} (\text{dBm}) = kTB(\text{dBm}) + F_{receiver} (\text{dB}) \\ \text{Sensitivity} &= P_{in,min} (\text{dBm}) = kTB(\text{dBm}) + F_{receiver} (\text{dB}) + SNR_{min} (\text{dB}) \\ &= P_{nf} (\text{dBm}) + SNR_{min} (\text{dB}) \end{aligned}$$



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Sensitivity Example



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Calculate Receiver Noise Figure

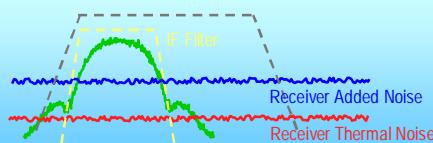
- Stage Thermal Noise
- Image Noise
- LO Wideband Phase Noise

$$F_{tot} = 1 + \frac{F_1 - 1}{1} + \frac{F_2 - 1}{G_1} + \frac{F_3 - 1}{G_1 G_2} + \frac{F_4 - 1}{G_1 G_2 G_3} + L$$

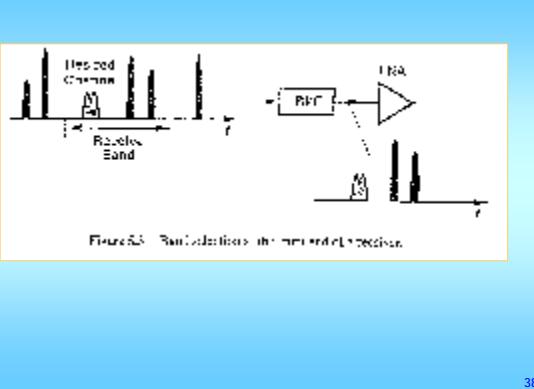
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Selectivity

- IF filter rejection at the adjacent channel
- LO spurious in IF bandwidth
- Phase noise of LO

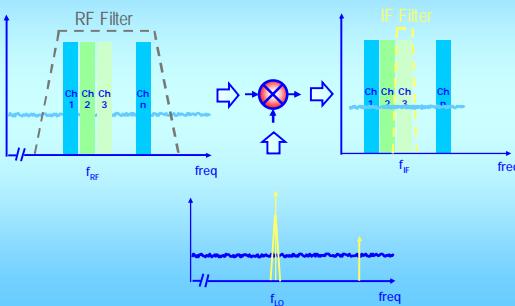


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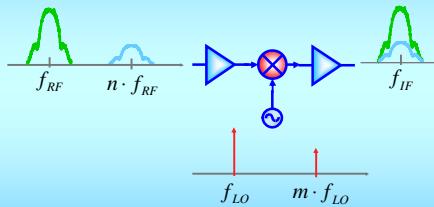
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Selectivity



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Spurious Response



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Spurious Responses

$$IF = n \cdot RF + m \cdot LO$$

$$\frac{IF}{RF} = m \cdot \frac{LO}{RF} + n$$

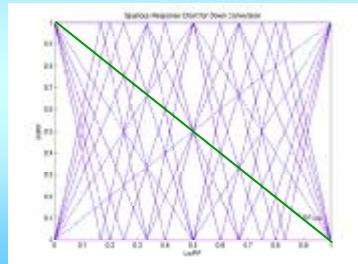
$$y = \frac{IF}{RF}, x = \frac{LO}{RF}$$

$$y = m \cdot x + n$$

$$|m| + |n| = \text{order of spurious response}$$

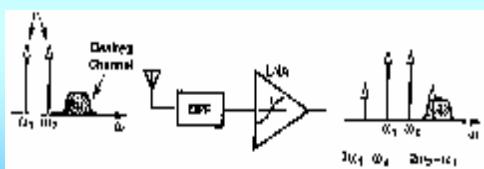
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Spurious Response Chart



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- Nonlinearity and Spurious response



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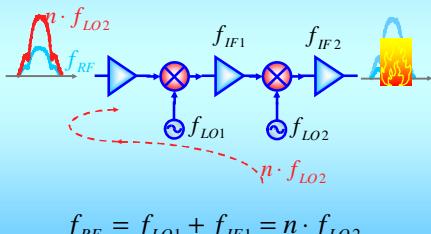
Intermodulation Rejection



$$IP3_{output} = \frac{1}{\sum_i \frac{1}{IP3_i G_{i+1} G_{i+2} \mathbf{L}_i G_n}} \text{ (mW)}$$

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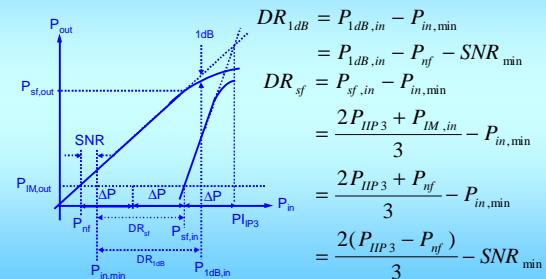
Receiver Self-quieting



$$f_{RF} = f_{LO1} + f_{IF1} = n \cdot f_{LO2}$$

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Dynamic Range



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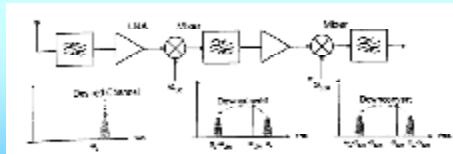
Receiver Architectures

- Heterodyne Receiver
- Direct Conversion Receiver
- Low-IF Receiver
- Image Reject Receiver

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Super-heterodyne Receiver

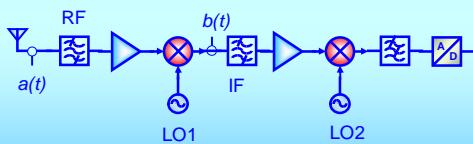
- easy to design
- problem of image
- problem of half IF



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Heterodyne Receiver

- IF receiver



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Problem of Image Signal

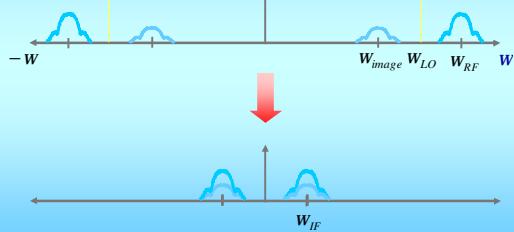
$$\begin{aligned}
 a(t) &= \cos(w_x t + m(t) + f) \\
 b(t) &= a(t) \cdot \cos(w_{LO} t + q) \\
 &= \cos(w_x t + m(t) + f) \cdot \cos(w_{LO} t + q) \\
 &= \frac{1}{2} \cos((w_x + w_{LO})t + m(t) + f + q) \\
 &\quad + \frac{1}{2} \cos((w_x - w_{LO})t + m(t) + f - q)
 \end{aligned}$$

if $w_x = w_{RF} = w_{LO} + w_{IF} \Rightarrow OK$

if $w_x = w_{image} = w_{LO} - w_{IF} \Rightarrow ?$

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Problem of Image Signal

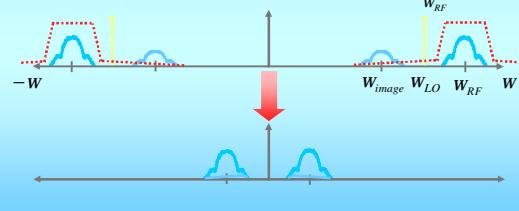


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Problem of Image Signal

- One solution: Image Rejection Filter

$$\text{Image rejection ratio: } \frac{H_{IR}(w_{RF})}{H_{IR}(w_{image})} = \frac{1}{\bar{H}_{IR}(\frac{w_{image}}{w_{RF}})}$$



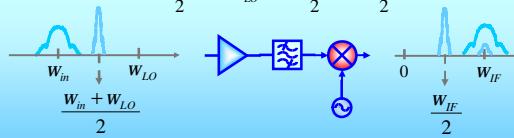
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Problem of Half IF

- Second order harmonic

$$|(w_{in} + w_{LO}) - 2w_{LO}| = w_{IF}$$

$$\frac{w_{in} + w_{LO} - w_{LO}}{2} = \frac{w_{in} - w_{LO}}{2} = \frac{w_{IF}}{2}$$



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How to Select IF?

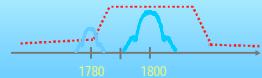
- Spurious Response
- Image Rejection v.s. Channel Selection
- Filter Availability

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Filter Availability

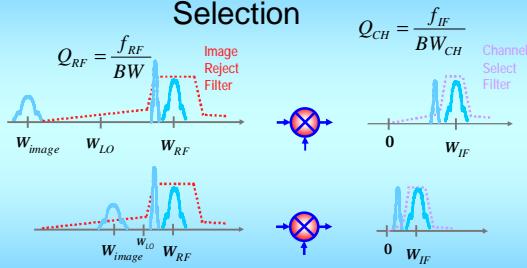
- Example 1
 - $f_{RF}=1800\text{MHz}$
 - $f_{IF}=10\text{MHz}$
 - Is this filter available?

$$\frac{f_{RF}}{f_{IF}} = 180 \quad Q = \frac{f_{RF}}{BW} \geq \frac{1800}{20} = 90$$



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Image Rejection v.s. Channel Selection

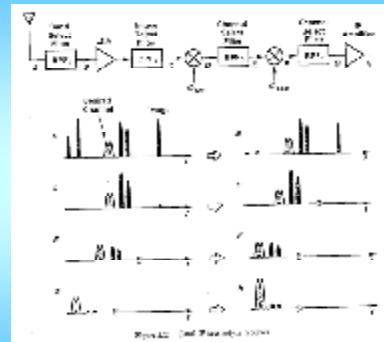


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IF Selection

- Usually $f_{RF}/f_{IF} < 10$
- Example 2 (Multistage IF)
 - $f_{RF}=900\text{MHz}$
 - $f_{IF1}=250\text{MHz}$
 - $f_{IF2}=50\text{MHz}$
 - $f_{IF3}=10\text{MHz}$

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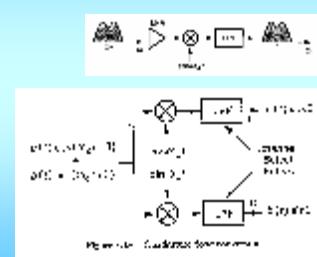
Summary of Heterodyne Receiver

- Down converts RF to IF thus introduces image problem; avoid image signal by image reject filter
- As frequency / bandwidth increases, multi-stage IF is necessary
- Not suitable for integration due to off-chip filters
- Sensitive to external parasitic signal
- Expensive and high power consumption

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Direct Conversion Receivers

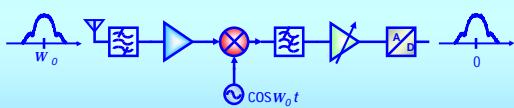
- Easy to single chip
- Channel Selection
- DC offsets
- I/Q Mismatch
- Even-Order Distortion
- Flick Noise:choose a suitable code
- LO Leakage



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Direct Conversion Receiver

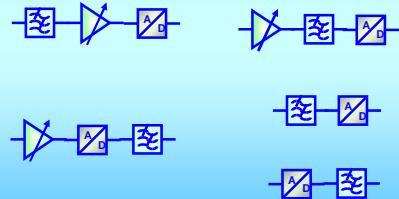
- Zero-IF Receiver



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Channel Selection

- Different placement of three block



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Comparison and trade-offs

- Assume normalized input full range of +/- 1V for the ADC
- Input signal (signal after mixer) amplitude can range from ~<1 mV to just under 1V
- $f_{RF}=1.8\text{GHz}$, $f_{IF}=100\text{MHz}$, $f_{ch}=200\text{KHz}$
- Input signal is wideband but the desired signal component is narrow band (IF)
- DSP in digital domain is omnipotent

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BPF

- Good Q(>25), excellent dynamic range
 - Blocks unwanted channels
- AGC amplifier
 - Only need to maintain in-channel linearity
 - Example gains: 1, 4, 16, 64, 250, 1000
 - Ensures $V_{inADC} \frac{1}{4}$ to full range
- ADC
 - 6 bit is sufficient, this gives at least:
 - 16 quantization levels for $\frac{1}{4}$ full range
 - Can do sub-sampling, =>low speed ADC: ADC speed >400KSPS

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- AGC amplifier
 - Need excellent dynamic range and wide band linearity
 - Example gains: 1, 4, 16, 64, 250, 1000
 - Ensures $V_{inBPF} \frac{1}{4}$ to full range
- BPF
 - Good Q(>25), but no need for high dynamic range
 - Blocks unwanted channels
- ADC
 - 6 bit is sufficient, this gives at least:
 - 16 quantization levels for $\frac{1}{4}$ full range
 - Can do sub-sampling, => low speed ADC: ADC speed >400KSPS

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AGC amplifier

- Need excellent dynamic range and wide band linearity
 - Example gains: 1, 4, 16, 64, 250, 1000
 - Ensures $V_{inBPF} \frac{1}{4}$ to full range
- ADC
 - 6 bit is sufficient, this gives at least:
 - 16 quantization levels for $\frac{1}{4}$ full range
 - But need high-speed ADC: ADC speed >200MSPS
- BPF
 - Implement in DSP domain

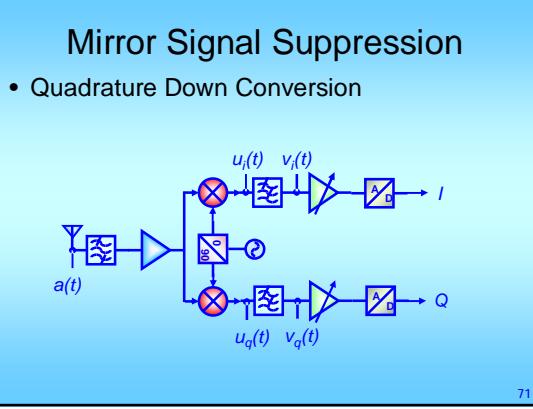
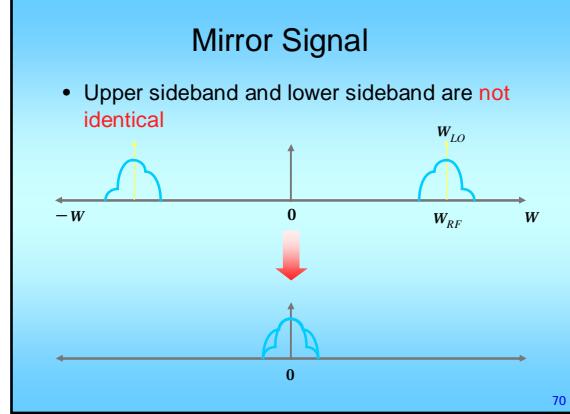
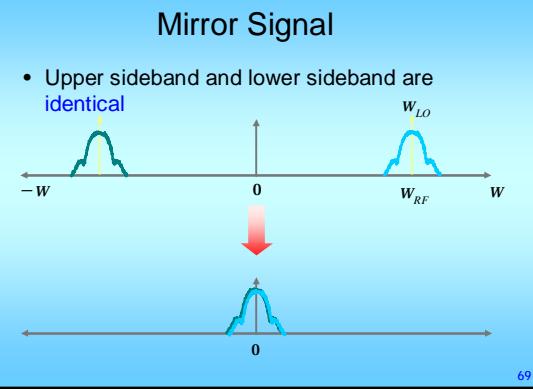
66

- BPF
 - Good Q(>25), excellent dynamic range
 - Blocks unwanted channels
 - But ADC input ranges from sub mV to 1V
- ADC
 - High resolution is required
 - At least 16 bits to ensure 16 quantization levels for $\frac{1}{4}$ mV weak signals
 - Narrow band allows sub-sampling, =>low speed ADC: ADC speed >400KSPS
 - Currently 16 bit 1-5MSPS ADCs available
- No AGC amplifier used

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- ADC
 - ADC input ranges from sub mV to 1V
 - High resolution is required
 - At least 16 bits to ensure 16 quantization levels for $\frac{1}{4}$ mV weak signals
 - Full IF band requires high-speed ADC: ADC speed >200MSPS
 - Currently 12 bit 200MSPS ADCs available, which gives 4 quantization levels for 1mV signals
- BPF
 - Implement in DSP domain
- No AGC amplifier used

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Quadrature Conversion

$$a(t) = \cos(\omega_{RF}t + m(t) + f)$$

$$u_i(t) = a(t) \cdot \cos(\omega_{LO}t + q)$$

$$u_q(t) = a(t) \cdot \sin(\omega_{LO}t + q)$$

$$v_i(t) = \frac{1}{2} \cos(m(t) + f - q)$$

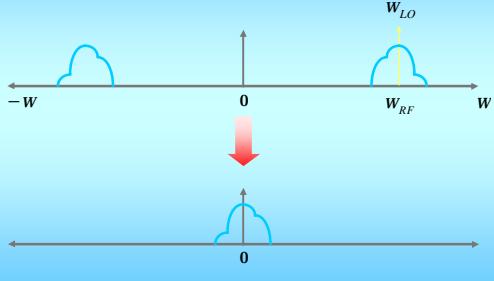
$$v_q(t) = \frac{-1}{2} \sin(m(t) + f - q)$$

$$\frac{v_q(t)}{v_i(t)} = \tan(-m(t) + q - f)$$

$$m(t) = -\tan^{-1}\left(\frac{v_q(t)}{v_i(t)}\right) + q - f$$

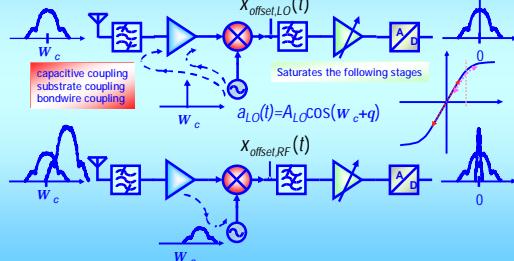
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Quadrature Down Conversion



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DC Offset (Self-mixing)



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DC Offset (Self-mixing)

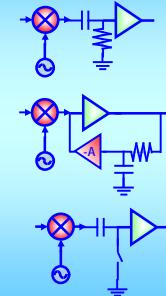
$$\begin{aligned} x_{\text{offset},LO}(t) &= A_{\text{crosstalk}}(\omega) \cdot a_{LO}(t) \cdot a_{LO}(t) \\ &= A_{\text{crosstalk}}(\omega) \cdot A_{LO} \cos(\omega_c t + \theta) \cdot A_{LO} \cos(\omega_c t + \theta) \\ &= \frac{1}{2} \cdot A_{\text{crosstalk}}(\omega) \cdot A_{LO}^2 (1 + \cos 2(\omega_c t + \theta)) \\ x_{\text{offset},\text{interferer}}(t) &= A_{\text{crosstalk}}(\omega) \cdot a_{\text{interferer}}(t) \cdot a_{\text{interferer}}(t) \\ &= A_{\text{crosstalk}}(\omega) \cdot A_{\text{interferer}}^2 \cos^2(\omega_c t + m(t) + \varphi) \\ &= \frac{1}{2} \cdot A_{\text{crosstalk}}(\omega) \cdot A_{\text{interferer}}^2 (1 + \cos 2(\omega_c t + m(t) + \varphi)) \end{aligned}$$



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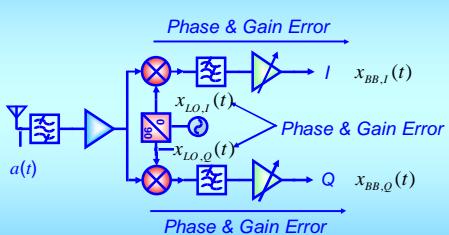
DC Offset Cancellation

- Capacitive Coupling
 - Requires a large capacitor
- Negative Feedback
 - Nonlinear
- TDMA Offset Cancellation
 - Requires a large capacitor



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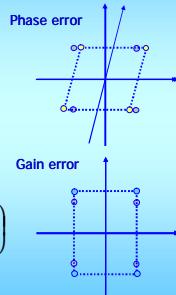
I/Q Mismatch



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I/Q Mismatch

$$\begin{aligned} a(t) &= A \cos(\omega_c t + m(t) + f) \\ x_{LO,I}(t) &= \left(1 + \frac{e}{2}\right) \cos\left(\omega_c t + \frac{q}{2}\right) \\ x_{LO,Q}(t) &= \left(1 - \frac{e}{2}\right) \sin\left(\omega_c t - \frac{q}{2}\right) \\ x_{BB,I}(t) &= \frac{A}{2} \left(1 + \frac{e}{2}\right) \cos\left(m(t) + f - \frac{q}{2}\right) \\ x_{BB,Q}(t) &= -\frac{A}{2} \left(1 - \frac{e}{2}\right) \sin\left(m(t) + f + \frac{q}{2}\right) \end{aligned}$$



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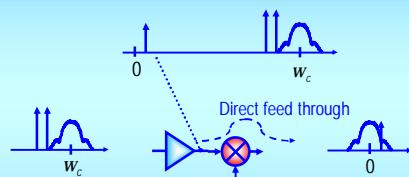
$$x_{BB,I}(t) = a\left(1 + \frac{e}{2}\right)\cos\frac{q}{2} - b\left(1 + \frac{e}{2}\right)\sin\frac{q}{2}$$

$$x_{BB,Q}(t) = -a\left(1 - \frac{e}{2}\right)\sin\frac{q}{2} + b\left(1 - \frac{e}{2}\right)\cos\frac{q}{2}$$



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Even-Order Distortion



Direct feed through

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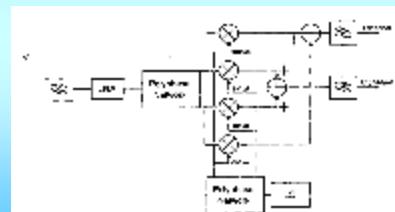
Summary of Direct Conversion Receiver

- No need for imager reject filter
- Suitable for monolithic integration with baseband
- DC offsets due to crosstalk of input ports of mixer
- Even order IM direct feed through to baseband
- Quadrature down conversion suppresses mirror
- I/Q mismatch due to mismatches in parasitics
- Low power consumption attributed to less hardware

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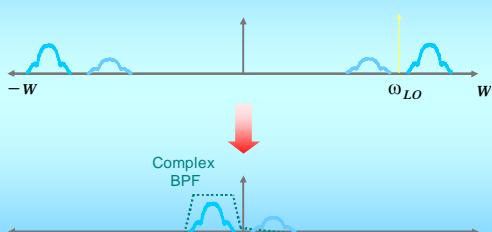
Low-IF Receivers

- Possible way to implant digital IF
- Low-IF cause image reject problem



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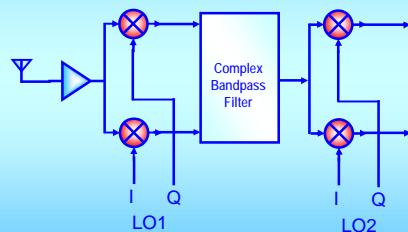
Low-IF Down Conversion



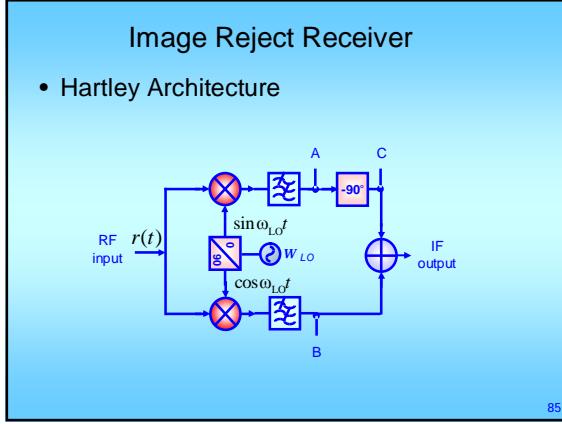
83

Mirror Signal Suppression (1)

Image Reject Receiver



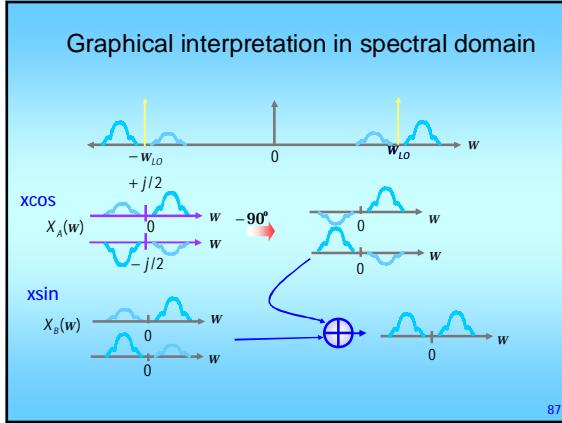
84



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$$\begin{aligned}
 r(t) &= A_{RF} \cos w_{RF} t + A_{im} \cos w_{im} t \\
 x_A(t) &= \frac{A_{RF}}{2} \sin(w_{LO} - w_{RF})t + \frac{A_{im}}{2} \sin(w_{LO} - w_{im})t \\
 &= -\frac{A_{RF}}{2} \sin(w_{RF} - w_{LO})t + \frac{A_{im}}{2} \sin(w_{LO} - w_{im})t \\
 x_C(t) &= +\frac{A_{RF}}{2} \cos(w_{RF} - w_{LO})t - \frac{A_{im}}{2} \cos(w_{LO} - w_{im})t \\
 x_B(t) &= \frac{A_{RF}}{2} \cos(w_{LO} - w_{RF})t + \frac{A_{im}}{2} \cos(w_{LO} - w_{im})t \\
 x_{IFoutput}(t) &= A_{RF} \cos(w_{LO} - w_{RF})t = A_{RF} \cos w_{IF} t
 \end{aligned}$$

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- ### IQ error effect
- Ideal IQ: image completely rejected
 - If signal and image not single tone, 90° shift is not exact
 - Local oscillator's sine and cosine not matched in magnitude and phase
 - 90° phase shifter may have both gain and phase error
 - All lead to incomplete image rejection

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IPR Evaluation and IRR – LO error

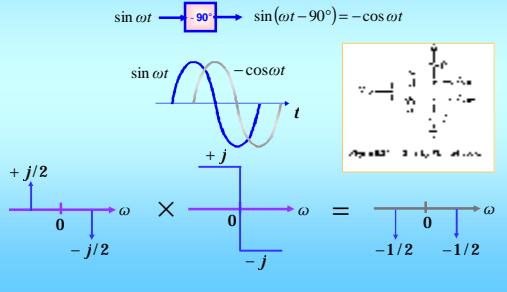
$$\begin{aligned}
 x_A(t) &= \frac{A_{LO}A_{RF}}{2} \sin(w_{LO} - w_{RF})t + \frac{A_{LO}A_{im}}{2} \sin(w_{LO} - w_{im})t \\
 x_B(t) &= (A_{LO} + e) \frac{A_{RF}}{2} \cos[(w_{LO} - w_{RF})t + q] + (A_{LO} + e) \frac{A_{im}}{2} \cos[(w_{LO} - w_{im})t + q] \\
 x_C(t) &= A_{LO} \left[\frac{A_{RF}}{2} \cos(w_{LO} - w_{RF})t - \frac{A_{im}}{2} \cos(w_{LO} - w_{im})t \right] \\
 x_{sig}(t) &= \frac{(A_{LO} + e)A_{RF}}{2} \cos[(w_{LO} - w_{RF})t + q] + \frac{A_{LO}A_{RF}}{2} \cos(w_{LO} - w_{RF})t \\
 x_{im}(t) &= \frac{(A_{LO} + e)A_{im}}{2} \cos[(w_{LO} - w_{im})t + q] - \frac{A_{LO}A_{im}}{2} \cos(w_{LO} - w_{im})t
 \end{aligned}$$

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$$\begin{aligned}
 \left| \frac{P_{im}}{P_{sig}} \right|_{out} &= \frac{A_{im}^2 (A_{LO} + e)^2 - 2A_{LO}(A_{LO} + e)\cos q + A_{LO}^2}{A_{RF}^2 (A_{LO} + e)^2 + 2A_{LO}(A_{LO} + e)\cos q + A_{LO}^2} \\
 &\quad \text{Input image power ratio} \\
 IRR &= \frac{(A_{LO} + e)^2 - 2A_{LO}(A_{LO} + e)\cos q + A_{LO}^2}{(A_{LO} + e)^2 + 2A_{LO}(A_{LO} + e)\cos q + A_{LO}^2} \\
 &= \frac{(1 + \frac{\Delta A}{A})^2 - 2(1 + \frac{\Delta A}{A})\cos q + 1}{(1 + \frac{\Delta A}{A})^2 + 2(1 + \frac{\Delta A}{A})\cos q + 1} \\
 IRR &\approx \frac{(\Delta A/A)^2 + q^2}{4} \quad \theta \text{ in radians}
 \end{aligned}$$

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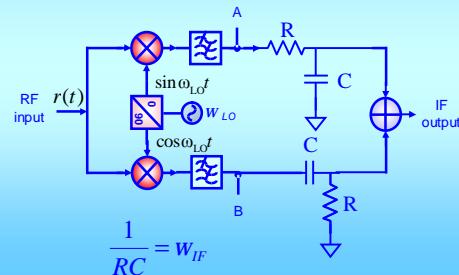
90 degree phase shift



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Image Reject Receiver

- Hartley Architecture



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Gain Mismatch Due to RC errors:

$$\frac{\Delta A}{A} = \frac{(R + \Delta R)(C + \Delta C)W - 1}{\sqrt{1 + (R + \Delta R)^2(C + \Delta C)^2}W^2} \div \frac{1}{\sqrt{1 + R^2C^2W^2}}$$

$$\begin{aligned} \frac{\Delta A}{A} &\approx \frac{\Delta R/R + \Delta C/C}{\sqrt{2 + \Delta R/R + \Delta C/C}} \div \frac{1}{\sqrt{2}} \\ &\approx \frac{\Delta R}{R} + \frac{\Delta C}{C} \end{aligned}$$

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- Check IEL for "polyphase filter" or "image reject filter"

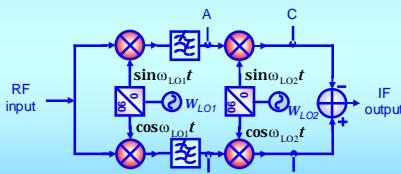
- All suffer from error due to frequency mismatch if signal is not pure single tone

- For 90° phase shifter for LO, there are several alternatives
 - Differential ring oscillators with even # of delay stages
 - D-FF based phase delays
 - Double-integrator based oscillators
 - Delay-locked loops
 - Phase-locked loops

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Image Reject Receiver

- Weaver Architecture



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$$x(t) = A_{RF} \cos[w_{RF}t + q_1] + A_{im} \cos[w_{im}t + q_2]$$

$$\begin{aligned} x_A(t) &= \frac{A_{RF}}{2} \sin[(w_{LO1} - w_{RF})t - q_1] + \frac{A_{im}}{2} \sin[(w_{LO1} - w_{im})t - q_2] \\ &= -\frac{A_{RF}}{2} \sin[(w_{RF} - w_{LO1})t + q_1] + \frac{A_{im}}{2} \sin[(w_{LO1} - w_{im})t - q_2] \end{aligned}$$

$$\begin{aligned} x_B(t) &= \frac{A_{RF}}{2} \cos[(w_{LO1} - w_{RF})t - q_1] + \frac{A_{im}}{2} \cos[(w_{LO1} - w_{im})t - q_2] \\ &= \frac{A_{RF}}{2} \cos[(w_{RF} - w_{LO1})t + q_1] + \frac{A_{im}}{2} \cos[(w_{LO1} - w_{im})t - q_2] \end{aligned}$$

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$$x_C(t) = x_A(t) \sin w_{LO2} t$$

$$= -\frac{A_{RF}}{4} \cos[(w_{RF} - w_{LO1} - w_{LO2})t + q_1]$$

$$+ \frac{A_{im}}{4} \cos[(w_{LO1} - w_{im} - w_{LO2})t - q_2]$$

$$x_D(t) = x_B(t) \cos w_{LO2} t$$

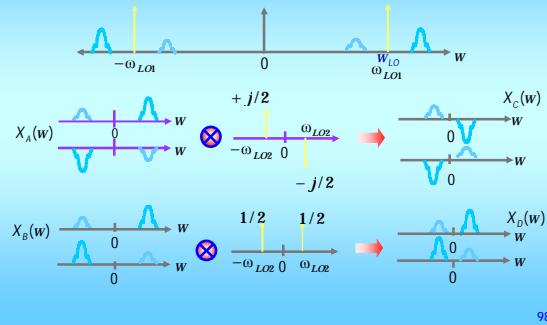
$$= \frac{A_{RF}}{4} \cos[(w_{RF} - w_{LO1} - w_{LO2})t + q_1]$$

$$+ \frac{A_{im}}{4} \cos[(w_{LO1} - w_{im} - w_{LO2})t - q_2]$$

$$x_{output}(t) = x_D(t) - x_C(t) = \frac{A_{RF}}{2} \cos[(w_{RF} - w_{LO1} - w_{LO2})t + q_1]$$

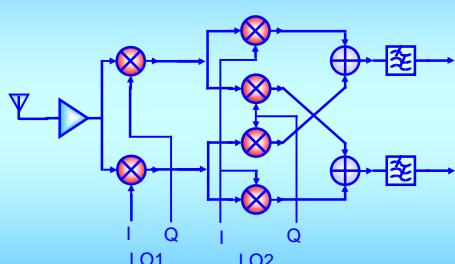
97

Weaver Architecture



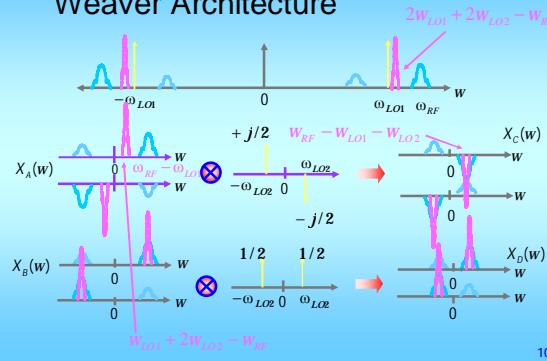
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Quadrature Weaver Architecture



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Weaver Architecture



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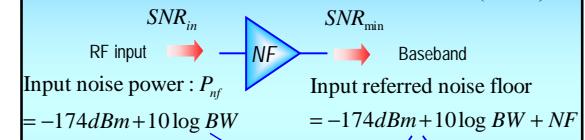
Receiver Link Budget Analysis

- Noise Figure Calculation
- IP3 Calculation
- Image Rejection Calculation
- Frequency Planning

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Noise Figure Calculation

$$SNR_{min} = \frac{E_s}{N_0} \cdot \frac{R_{symbol}}{BW} \Rightarrow SNR_{min} (dB) = \frac{E_s}{N_0} (dB) + 10 \log \left(\frac{R_{symbol}}{BW} \right)$$



Standard	Bandwidth: \$10 \log(BW)\$	Sensitivity(dBm)	Noise Floor (dBm)	\$SNR_{in}(dB)\$	\$NF(dB)\$	\$SNR_{min}(dB)\$
DECT	1.70E+06	62.30	-83.00	-111.50	28.50	18.20
GSM	2.00E+05	53.01	-102.00	-120.79	18.79	9.79
WLAN	2.00E+06	63.01	-80.00	-110.79	30.79	15.1

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IP3 Calculation

$$DR_{sf} = \frac{2(P_{IIP3} - P_{nf})}{3} - SNR_{min}$$

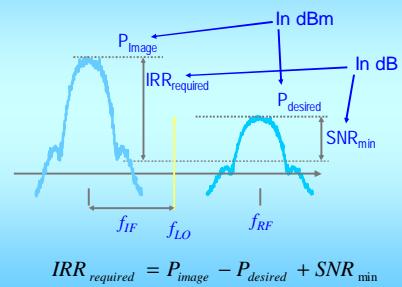
$$P_{IIP3} = \frac{3}{2}(DR_{sf} + SNR_{min}) + P_{nf}$$

$$P_{-1dB} \approx P_{IIP3} - 10$$

Standard	DR	SFDR	IIP3	Pmax	Bandwidth	$10\log(BW)$	Sensitivity(dBm)
Bluetooth	50.00	36.57	-10.00	-20.00	1.00E+06	60.00	-70.00
GSM	87.00	61.67	-5.00	-15.00	2.00E+05	53.01	-102.00
WLAN	76.00	52.30	6.00	-4.00	2.00E+06	63.01	-80.00

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Image Rejection Calculation



$$IRR_{required} = P_{image} - P_{desired} + SNR_{min}$$

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