# EE 508Lecture 6

## Filter Concepts/Terminology Approximation Problem

## Root characterization in s-plane (for complex-conjugate roots)



For high Q, θ is small

### Root characterization in s-plane (for complex-conjugate roots)



roots located at

# Filter Concepts and Terminology

- $\blacktriangleright$  Frequency scaling
	- $\blacktriangleright$  Frequency Normalization
		- Impedance scaling
		- Transformations
			- LP to BP
			- LP to HP
			- LP to BR

## Frequency Scaling and normalization

Frequency normalization:

$$
s_n = \frac{s}{\omega_0}
$$

Frequency scaling:  $s = \omega_0 s_n$ 

Purpose:

 $\omega_{\rm o}$  independent approximations

 $\omega_{\rm o}$  independent synthesis

Simplifies analytical expressions for T(s)

Simplifies component values in synthesis

Use single table of normalized filter circuits for given normalized approximating function

Note: The normalization subscript "n" is often dropped

$$
T(s) = \frac{6000}{s + 6000}
$$



Normalized transfer function:

$$
T_n(s_n) = \frac{1}{s_n + 1}
$$



$$
T_n(s_n) = \frac{1}{s_n + 1}
$$



Synthesis of normalized function







Frequency scaling by  $\omega_{0}$  (of transfer function)

s = ω<sub>0</sub>s<sub>n</sub>



Frequency scaling by  $\omega_{0}^{}$  (of energy storage elements in circuit)





Frequency scaling / normalization does not change the shape of the transfer function, it only scales the frequency axis linearly

The frequency scaled circuit can be obtained from the normalized circuit simply by scaling the frequency dependent impedances (up or down) by the scaling factor

This makes the use of filter design tables for the design of lowpass filters practical whereby the circuits in the table all have a normalized band edge of 1 rad/sec.

## Frequency normalization/scaling

Example: Table for passive ladder Butterworth filter with 3dB band edge of 1 rad/sec





LOW DASS RIEMENT VALUES

## Frequency normalization/scaling

The frequency scaled circuit can be obtained from the normalized circuit simply by scaling the frequency dependent impedances (up or down) by the scaling factor

Component denormalization by factor of  $\omega_{_0}$ 



**Component values of energy storage elements are scaled down by a factor of ω 0**

## Desgin Strategy

Theorem: A circuit with transfer function T(s) can be obtained from a circuit with normalized transfer function  $T_n(s_n)$  by denormalizing all frequency dependent components.

> $C \longrightarrow C/\omega_{\alpha}$  $L \longrightarrow L \omega_0$

Example: Design a V-V passive 3rd-order Lowpass Butterworth filter with a band-edge of 1K Rad/Sec and equal source and load terminations.



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Is this solution practical?

#### **Some component values are too big and some are too small !**

# Filter Concepts and Terminology

- Frequency scaling
- Frequency Normalization
- • Impedance scaling
	- Transformations
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# Impedance Scaling

Impedance scaling of a circuit is achieved by multiplying ALL impedances in the circuit by a constant



 $\theta A$  for transresistance gain  $A \longrightarrow A$  for dimensionless gain  $A/\theta$  for transconductance gain

# Impedance Scaling

Theorem: If all impedances in a circuit are scaled by a constant θ, then

- a) All dimensionless transfer functions are unchanged
- b) All transresistance transfer functions are scaled by θ
- c) All transconductance transfer functions are scaled by θ-1

# Impedance Scaling



 $\boldsymbol{\mathsf{(s)}}$ 1 $\mathsf{T}(\mathsf{s}) = \frac{\cdot}{\mathsf{s}+\mathsf{1}}$ 

T(s) is dimensionless

Impedances scaled by θ=10 $^5$ 

**100K**  $V_{\rm OUT}$ 1 $\boldsymbol{\mathsf{(s)}}$  $\mathsf{T}(\mathsf{s}) = \frac{\cdot}{\mathsf{s}+\mathsf{1}}$  $V_{IN}$  $\overleftarrow{\sim}$ 10uF

Note second circuit much more practical than the first

Example: Design a V-V passive 3rd-order Lowpass Butterworth filter with a band-edge of 1K Rad/Sec and equal source and load terminations.



 $\theta$ R

Is this solution practical?

#### **Some component values are too big and some are too small !**

R

Impedance scale by θ=1000



Component values more practical

## Typical approach to lowpass filter design

- 1. Obtain normalized approximating function
- 2. Synthesize circuit to realize normalized approximating function
- 3. Denormalize circuit obtained in step 2
- 4. Impedance scale to obtain acceptable component values

Note: We have not discussed the Butterworth approximation yet so some details here will be based upon concepts that will be developed later

$$
T_{\text{BWh}} = \left(\frac{1}{s^2 + \sqrt{2}s + 1}\right) \cdot 5
$$





8 design variables and only two constraints (ignoring the gain right now)







Normalizing by the factor  $\omega_0$ , we obtain

$$
T(s_n) = \frac{1}{s^2 + s\left(\frac{1}{Q}\right) + 1}
$$

Setting R=C=1 obtain the following normalized circuit



$$
T(s_n) = \frac{1}{s^2 + s(\frac{1}{Q}) + 1}
$$
  $\omega_{0n} = 1$ 

Must now set *Q* <sup>=</sup>

Now we can do frequency scaling  $C/\omega_{\alpha}$  $\mathsf{L}\omega_{\alpha}$  $C=1 \rightarrow 1/(2\pi \cdot 4K) = 39.8$ uF

2

Denormalized circuit with bandedge of 4 KHz



This has the right transfer function (but unity gain)

Can now do impedance scaling to get more practical component values

 $AR$  $\rightarrow$  C/A - AL

A good impedance scaling factor may be θ=1000

$$
R \longrightarrow 1K
$$
  

$$
C \longrightarrow 39.8nF
$$

Denormalized circuit with bandedge of 4 KHz



This has the right transfer function (but unity gain)

To finish the design, preceed or follow this circuit with an amplifier with a gain of 5 to meet the dc gain requirements